# **Temperature Control for Langevin Diffusions**

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## **Langevin Diffusion for Global Non-convex Optimization**

- Global non-convex optimization:  $\min_{x \in \mathbb{R}^d} f(x)$ .
- Gradient descent may converge to a suboptimal local minimum.
- Continuous Langevin algorithm or overdamped Langevin diffusion:

$$dX(t) = \underbrace{-f_X(X(t))dt}_{\text{Gradient descent}} + \underbrace{\sqrt{2\beta(t)}dW(t)}_{\text{Brownian noise}}, \quad t \ge 0.$$

- Problem: design endegeneous state-dependent temperature  $\beta(t)$ .
- The classical optimal control of such a problem is of the bang-bang type, which is overly sensitive to any errors.

### **Exploratory Control Formulation**

• We study the entropy-regularized stochastic relaxed control problem:

$$V(x) = \inf_{\pi \in \mathcal{A}(x)} \mathbb{E}\left[\int_0^\infty e^{-\rho t} f(X^{\pi}(t)) dt - \lambda \int_0^\infty e^{-\rho t} \int_U -\pi(t, u) \ln \pi(t, u) du dt\right],$$

- $\int_U -\pi(t,u) \ln \pi(t,u) du$ : the differential entropy of the probability density function  $\pi(t,\cdot)$  of the randomized temperature,
- *U*: the range of the temperature,
- $\lambda > 0$ : a weight parameter measures the strength of regularization,
- $X^{\pi}$  is governed by

$$dX^\pi(t)=-f_{\!\scriptscriptstyle X}(X^\pi(t))dt+\sigma(\pi(t))dW(t), \ \ X^\pi(0)=x,$$
 where  $\sigma(\pi):=\sqrt{\int_U 2u\pi(u)du}.$ 

#### Results

• Optimal feedback law is truncated exponential distribution:

$$ar{\pi}(u;x) = rac{1}{Z(\lambda, v_{xx}(x))} \exp\left(-rac{1}{\lambda}[\operatorname{tr}(v_{xx}(x))u]
ight), \quad u \in U,$$

where v satisfies the equation

$$-\rho v(x) - f_x(x) \cdot v_x(x) + f(x) - \lambda \ln(Z(\lambda, v_{xx}(x))) = 0, \quad x \in \mathbb{R}^d.$$

Optimal state process

$$dX^*(t) = -f_X(X^*(t))dt + h(X^*(t))dW(t),$$

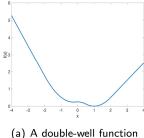
where

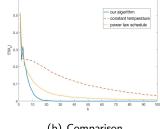
$$h(x) := \sqrt{\frac{2}{Z(\lambda, v_{xx}(x))} \int_{U} u \exp\left(-\frac{1}{\lambda} [\operatorname{tr}(v_{xx}(x))u]\right) du}.$$

### **Algorithm and Numerical Example**

Comparison of three algorithms on a baseline non-convex function

- Langevin algorithm with constant temperature
- Langevin algorithm with power-law temperature schedule
- Our algorithm with state-dependent temperature





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(b) Comparison

### **Research Support**

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